



8.2 Similarity and diagonalizability

Coordinate change for diagonalization

Similar matrices

Definition 8.2.1 If A and C are square matrices with the same size, then we say that C is *similar to* A if there is an invertible matrix P such that $C = P^{-1}AP$.

- $A \approx B, B \approx C \rightarrow A \approx C$. $A \approx A$. $A \approx B \rightarrow B \approx A$

Theorem 8.2.2 *Two matrices are similar if and only if there exist bases with respect to which the matrices represent the same linear operator.*

- **Proof:** $C = P^{-1}AP$. If $P = [v_1, \dots, v_n]$, then by equation (20) Sec.8.1, we have $[T]_B = P^{-1}[T]P$ where $[T] = A$.

Similarity Invariants

- Coordinate changes are superficial changes.
- Many essential properties remain.
- $\det(P^{-1}AP) = \det(P)^{-1} \det(A) \det(P) = \det(A)$.

Theorem 8.2.3

- (a) *Similar matrices have the same determinant.*
- (b) *Similar matrices have the same rank.*
- (c) *Similar matrices have the same nullity.*
- (d) *Similar matrices have the same trace.*
- (e) *Similar matrices have the same characteristic polynomial and hence have the same eigenvalues with the same algebraic multiplicities.*

- Example 1.



Eigenvectors and eigenvalues of similar matrices

- The algebraic multiplicity of an eigenvalue is the multiplicity as a root of the characteristic polynomial.
- The geometric multiplicity of an eigenvalue is the dimension of $(\lambda I - A)x = 0$.
- geom mult. \leq alg. mult.
- Example 2.

Theorem 8.2.4 *Similar matrices have the same eigenvalues and those eigenvalues have the same algebraic and geometric multiplicities for both matrices.*

- **Proof:** $C = P^{-1}AP$. Then
 - $LI - C = LI - P^{-1}AP = P^{-1}(LI - A)P$.
 - $\det(LI - C) = \det(LI - A)$.
 - $(LI - C)x = 0 \iff P^{-1}(LI - A)Px = 0 \iff (LI - A)y = 0$ for $y = Px$. (substitute variable)
 - Thus $\dim \text{sol } (LI - C)x = 0$ is the same as $\dim \text{sol } (LI - A)x = 0$.

Theorem 8.2.5 Suppose that $C = P^{-1}AP$ and that λ is an eigenvalue of A and C .

- (a) If \mathbf{x} is an eigenvector of C corresponding to λ , then $P\mathbf{x}$ is an eigenvector of A corresponding to λ .
- (b) If \mathbf{x} is an eigenvector of A corresponding to λ , then $P^{-1}\mathbf{x}$ is an eigenvector of C corresponding to λ .

- Proof (b): $A\mathbf{x} = \lambda\mathbf{x}$. $\rightarrow P^{-1}A\mathbf{x} = \lambda P^{-1}\mathbf{x}$
 $\rightarrow P^{-1}AP(P^{-1}\mathbf{x}) = \lambda(P^{-1}\mathbf{x})$
 $\rightarrow C(P^{-1}\mathbf{x}) = \lambda(P^{-1}\mathbf{x})$.

Diagonalization

- We wish to change coordinates so that the matrix is diagonal.
- This is not always possible.

The Diagonalization Problem Given a square matrix A , does there exist an invertible matrix P for which $P^{-1}AP$ is a diagonal matrix, and if so, how does one find such a P ? If such a matrix P exists, then A is said to be *diagonalizable*, and P is said to *diagonalize* A .

Theorem 8.2.6 *An $n \times n$ matrix A is diagonalizable if and only if A has n linearly independent eigenvectors.*

- Proof \rightarrow : $A = PDP^{-1}$ for a diagonal matrix D with diagonals L_1, L_2, \dots, L_n .
 - $AP = PD$. $P = [p_1, p_2, \dots, p_n]$
 - $AP = [Ap_1, Ap_2, \dots, Ap_n]$
 - $PD = [L_1 p_1, L_2 p_2, \dots, L_n p_n]$
 - Thus $Ap_i = L_i p_i$.
- Proof \leftarrow : p_1, p_2, \dots, p_n linearly independent, eigenvectors.
 - $Ap_i = L_i p_i$.
 - Let $P = [p_1, p_2, \dots, p_n]$.
 - The same computations show $AP = PD$.
 - Since P is invertible, $P^{-1}AP = D$.

A method for diagonalizing a matrix.

Diagonalizing an $n \times n$ Matrix with n Linearly Independent Eigenvectors

Step 1. Find n linearly independent eigenvectors of A , say $\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_n$.

Step 2. Form the matrix $P = [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_n]$.

Step 3. The matrix $P^{-1}AP$ will be diagonal and will have the eigenvalues corresponding to $\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_n$, respectively, as its successive diagonal entries.

- Example 4.

Linear independence of eigenvectors

Theorem 8.2.7 *If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ are eigenvectors of a matrix A that correspond to distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$, then the set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is linearly independent.*

- Thus, if some eigenvalues coincide, the corresponding eigenvectors may be dependent. (This is unless they are fundamental solutions.)

Some facts

Theorem 8.2.8 *An $n \times n$ matrix with n distinct real eigenvalues is diagonalizable.*

Theorem 8.2.9 *An $n \times n$ matrix A is diagonalizable if and only if the sum of the geometric multiplicities of its eigenvalues is n .*

Theorem 8.2.10 *If A is a square matrix, then:*

- (a) The geometric multiplicity of an eigenvalue of A is less than or equal to its algebraic multiplicity.*
- (b) A is diagonalizable if and only if the geometric multiplicity of each eigenvalue of A is the same as its algebraic multiplicity.*

- Unifying theorem:

Theorem 8.2.11 *If A is an $n \times n$ matrix, then the following statements are equivalent.*

- (a) *A is diagonalizable.*
- (b) *A has n linearly independent eigenvectors.*
- (c) *\mathbb{R}^n has a basis consisting of eigenvectors of A .*
- (d) *The sum of the geometric multiplicities of the eigenvalues of A is n .*
- (e) *The geometric multiplicity of each eigenvalue of A is the same as the algebraic multiplicity.*

