

# Lens-shaped totally geodesic ends of convex real projective manifolds

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## Abstract

Convex projective structures are generalizations of hyperbolic structures on  $n$ -manifolds (orbifolds).

- We will study totally geodesic ends of convex real projective  $n$ -manifolds (orbifolds) These are ends that we can compactify by totally geodesic orbifolds of codimension-one.

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- We also discuss the relationship to the globally hyperbolic space-times in flat Lorentz geometry.
- The lens-shaped radial ends which are dual to lens-shaped totally geodesic ends.

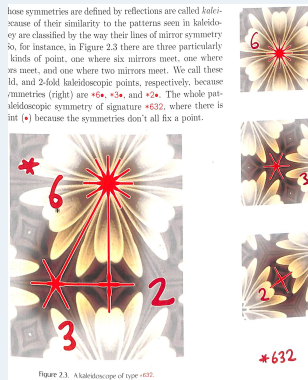
# Outline

- Introduction: orbifolds, geometric structures, projective, affine, and hyperbolic geometry, real projective structures
- Main result:
  - ▶ Totally geodesic ends
  - ▶ Asymptotically nice action
  - ▶ Outline of proof
  - ▶ Globally hyperbolic spacetime
- Duality and R-ends

# Orbifolds

- By an  $n$ -dimensional orbifold is a space modelled on finite quotients of open sets (with some compatibility conditions.)
- Let  $P$  be a convex polyhedron and we silver each side where the angles are of form  $\pi/n$ : *Coxeter orbifolds*.

These symmetries are defined by reflections are called *kaleidoscopes* because of their similarity to the patterns seen in kaleidoscopy. So, for instance, in Figure 2.3 there are three particularly interesting kinds of point, one where six mirrors meet, one where three meet, and one where two mirrors meet. We call these 1-fold, 2-fold and 3-fold kaleidoscopic points, respectively, because they have 1-fold, 2-fold and 3-fold kaleidoscopic symmetry, respectively. The whole kaleidoscopic symmetry of signature  $*632$ , where there is a 6-fold point, a 3-fold point, and a 2-fold point. The whole kaleidoscopic symmetry of signature  $*632$ , where there is a 6-fold point, a 3-fold point, and a 2-fold point. The whole kaleidoscopic symmetry of signature  $*632$ , where there is a 6-fold point, a 3-fold point, and a 2-fold point.

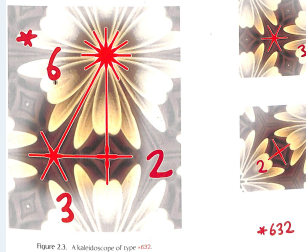




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- Let  $P$  be a convex polyhedron and we silver each side where the angles are of form  $\pi/n$ : *Coxeter orbifolds*.
- Examples: a square with silvered edges, a triangular orbifold (Conway's picture)
- A **good orbifold**:  $M/\Gamma$  where  $\Gamma$  is a discrete group with a properly discontinuous action.

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## $(G, X)$ -geometry

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## $(G, X)$ -structure on orbifolds

Given a manifold or orbifold  $M$ , we locally model  $M$  by open subsets of  $X$  or their finite quotients pasted by elements of  $G$ . The compatibility class of the atlas of charts is a  $(G, X)$ -structure on  $M$ .

## Projective, affine geometry

- $\mathbb{R}P^n = P(\mathbb{R}^{n+1}) = (\mathbb{R}^{n+1} - \{O\}) / \sim$  where  $\vec{v} \sim \vec{w}$  iff  $\vec{v} = s\vec{w}$  for  $s \in \mathbb{R} - \{0\}$ .
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$$\mathbb{A}^n \hookrightarrow \mathbb{R}P^n, \text{Aff}(\mathbb{A}^n) \hookrightarrow \text{PGL}(n+1, \mathbb{R}).$$

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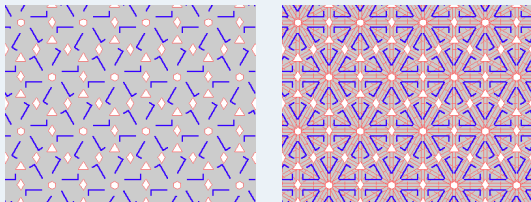


Figure: Wall-paper groups 16 and 17.

# Hyperbolic geometry

- $\mathbb{R}^{1,n}$  with Lorentzian metric  $q(\vec{v}) := -x_0^2 + x_1^2 + \cdots + x_n^2$ .
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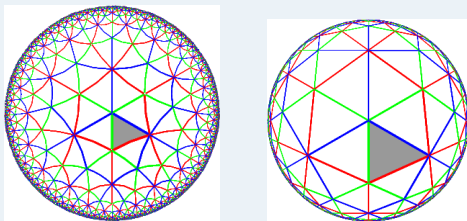


Figure: The triangle group  $D^2(3,3,4)$  in the Poincaré and Klein models by Bill Casselman.

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- The quotient  $D/\Gamma$  for a properly acting discrete group  $\Gamma \subset \mathbf{Aut}(D)$  is called a convex real projective orbifold.
- If  $D$  is properly convex, then  $D/\Gamma$  is called a *properly convex real projective orbifold*.

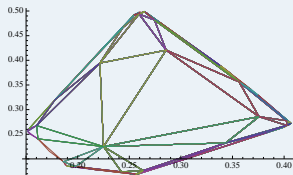
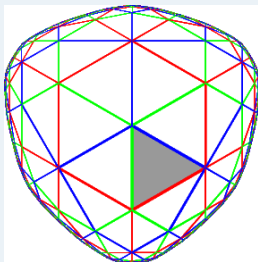


Figure: The developing images of convex  $\mathbb{R}P^n$ -structures on 2-orbifolds deformed from hyperbolic ones:  $D(3,3,4)$ ,  $S^2(3,3,5)$

# Oriented real projective space

- We can double cover to obtain  $\mathbb{S}^n \rightarrow \mathbb{RP}^n$ . The group of projective automorphisms is  $\mathrm{SL}_{\pm}(n+1, \mathbb{R})$ .
- Here,  $\mathbb{A}^n$  corresponds to an open hemisphere with ideal boundary  $\mathbb{S}_{\infty}^{n-1}$ .
- Every convex real projective structure on a closed orbifold can be thought of as being of form  $\Omega/\Gamma$  where  $\Omega$  is a convex domain in an open hemisphere. Hence, the holonomy of any closed curve can be uniquely chosen as an element of  $\mathrm{SL}_{\pm}(n+1, \mathbb{R})$ .
- The space of oriented hyperplanes in  $\mathbb{S}^n$  forms the dual space  $\mathbb{S}^{n*}$ .

## Totally geodesic ends

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A *totally geodesic end*, or T-end of a real projective orbifold  $\mathcal{O}$  is an end  $E$  admitting a compactification of a product end neighborhood whose ideal boundary component  $\Sigma_E$  is a totally geodesic orbifold. (Here, of course, with smooth str of such completion added to  $\mathcal{O}$ .)

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A *lens neighborhood* of  $\Sigma_E$  is a one-sided compact neighborhood of totally geodesic ideal boundary component in an ambient real projective orbifold covered by a lens.

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- $\Sigma_E$  is covered by an totally geodesic open  $n - 1$ -ball  $\tilde{\Sigma}_{\tilde{E}}$  associated with  $\tilde{E}$  and  $\Sigma_E = \tilde{\Sigma}_{\tilde{E}}/\Gamma_{\tilde{E}}$ .

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- In general these are somewhat related to the recent work of Cooper, Long, Tillman, Ballas, and Leitner.

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in  $Z^1(\Gamma, \mathbb{R}_{\hat{h}}^n)$ . This gives an affine map  $h(g) : x \mapsto \hat{h}(g)x + \vec{b}_g$  for each  $g \in \Gamma$ .

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- When  $\Gamma$  fixes a point or equivalently  $\vec{b} \sim 0$ ,  $U$  can be a cone.  $U$  can also be a properly convex domain with smooth boundary.

## Asymptotically nice action

### Definition 3.1 (AS-hyperspace).

A sharply supporting hyperspace  $P$  at  $x \in \text{bd}\Omega$  is *asymptotic* to  $U$  if there are no other sharply supporting hyperplane  $P'$  at  $x$  so that  $P' \cap \mathbb{A}^n$  separates  $U$  and  $P \cap \mathbb{A}^n$ .  $P$  is *asymptotic* to  $U$ .

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- $\Gamma$  acts on a compact subset  $J := \{H \mid H \text{ is an AS-hyperspace in } \mathbb{S}^n \text{ at } x \in \text{bd}\Omega, H \not\subset \mathbb{S}_{\infty}^{n-1}\}$ , requiring that every sharply supporting  $(n-2)$ -dimensional space of  $\Omega$  in  $\mathbb{S}_{\infty}^{n-1}$  is contained in an element of  $J$ .

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As a consequence, for any sharply supporting  $(n-2)$ -dimensional space  $Q$  of  $\Omega$ , the set

$$H_Q := \{H \in J \mid H \supset Q\}$$

is compact and bounded away from  $\text{bd}\mathbb{A}^n$  in the Hausdorff metric  $\mathbf{d}_H$ .

## Affine action

- For each element of  $g \in \Gamma_{\tilde{E}}$ , represented as a  $\det = \pm 1$  matrix,

$$h(g) = \begin{pmatrix} \frac{1}{\lambda_{\tilde{E}}(g)^{1/n}} \hat{h}(g) & \vec{b}_g \\ \vec{0} & \lambda_{\tilde{E}}(g) \end{pmatrix} \quad (1)$$

where  $\vec{b}_g$  is an  $n \times 1$ -vector and  $\hat{h}(g) \in \text{SL}_{\pm}(n, \mathbb{R})$  and  $\lambda_{\tilde{E}}(g) > 0$ .

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- In the affine coordinates, it is of the form

$$x \mapsto \frac{1}{\lambda_{\tilde{E}}(g)^{1+\frac{1}{n}}} \hat{h}(g)x + \frac{1}{\lambda_{\tilde{E}}(g)} \vec{b}_g. \quad (2)$$

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- For  $\lambda_1(g)$  the max-norm of the eigenvalues of  $g \in \Gamma_E$ , if there exists a uniform constant  $C > 1$  so that

$$C^{-1} \text{length}_{\Omega}(g) \leq \log \frac{\lambda_1(g)}{\lambda_{\tilde{E}}(g)} \leq C \text{length}_{\Omega}(g), \quad g \in \Gamma_{\tilde{E}} - \{I\}, \quad (3)$$

then  $\Gamma$  satisfies the *uniform middle eigenvalue condition* with respect to the boundary hyperspace.



# Asymptotic niceness

## Theorem 1.

We assume that  $\Gamma$  is a discrete affine group dividing an open properly convex domain  $\Omega$  in  $\text{bd}\mathbb{A}^n$ .

Suppose that  $\Gamma$  satisfies the uniform middle-eigenvalue condition with respect to  $\text{bd}\mathbb{A}^n$ .

Then

- $\Gamma$  is *asymptotically nice* with respect to a properly convex open domain  $U$ , and
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# Asymptotic niceness

## Theorem 1.

We assume that  $\Gamma$  is a discrete affine group dividing an open properly convex domain  $\Omega$  in  $\text{bd}\mathbb{A}^n$ .

Suppose that  $\Gamma$  satisfies the uniform middle-eigenvalue condition with respect to  $\text{bd}\mathbb{A}^n$ .

Then

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## Remark

Below, I give a proof for hyperbolic  $\Gamma$  or strictly convex  $\Omega$ . Here,  $\hat{\cup}\Omega = \cup\Omega$ .

# Hyperbolic and nonhyperbolic $\Gamma$ : dichotomy by Koszul, Vey, Benoist

Assume  $\Omega/\Gamma$  is a closed orbifold.

- ▶  $\Gamma$  is hyperbolic  $\leftrightarrow$
- ▶  $\Omega$  is strictly convex and have  $C^{1,\varepsilon}$ -boundary  $\rightarrow$
- ▶ each infinite order elements are positive proximal. (Benoist)

(Here unique supporting hyperplane for each  $x \in \text{bd}\Omega$ .)

# Hyperbolic and nonhyperbolic $\Gamma$ : dichotomy by Koszul, Vey, Benoist

Assume  $\Omega/\Gamma$  is a closed orbifold.

- Otherwise,  $\text{bd}\Omega$  may have flats and infinite order elements are only positive semiproximal.
  - ▶ decomposable: Here, we may have decomposition  $\text{Cl}(\Omega) = K_1 * \dots * K_m$  and  $\Gamma$  is virtually a subgroup of  $\mathbb{Z}^{m-1} \times \Gamma_1 \times \dots \times \Gamma_m$  with  $\mathbb{Z}^{m-1}$  in the center and positive diagonalizable.
  - ▶ nondecomposable: No virtual infinite center case: fairly nice properties.

(here, many supporting hyperplanes for each  $x \in \text{bd}\Omega$ .)

## Generalization of unit tangent bundles

We generalize  $\mathbb{U}\Omega$  to the *augmented unit tangent bundle*

$$\hat{\mathbb{U}}\Omega := \{(\vec{x}, H_a, H_r) \mid \vec{x} \in \mathbb{U}\Omega \text{ is a direction vector at a point}$$

of a maximal oriented geodesic  $l_{\vec{x}}$  in  $\Omega$ ,

$H_a$  is a sharply supporting hyperspace at the starting point of  $l_{\vec{x}}$ ,

$H_r$  is a sharply supporting hyperspace at the ending point of  $l_{\vec{x}}$ .} (4)

## Proximal flows

- the unit tangent space  $\mathbb{U}\Omega := T\Omega - O / \sim$ , affine space  $\mathbb{A}^n$  and associated vector space version  $\mathbb{R}^n$ .

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- $\tilde{\mathbf{A}} := \mathbb{U}\Omega \times \mathbb{A}^n$  with action

$$g(x, \vec{u}) = (g(x), h(g)\vec{u}) \text{ for } g \in \Gamma, x \in \mathbb{U}\Omega, \vec{u} \in \mathbb{A}^n.$$

The quotient space  $\mathbf{A}$  fibers over  $\mathbb{U}\Omega/\Gamma$  with fiber  $\cong \mathbb{A}^n$ .

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- $\tilde{\mathbf{V}} := \mathbb{U}\Omega \times \mathbb{R}^n$  and take the quotient under the diagonal action:

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The quotient space  $\mathbf{V}$  fibers over  $\mathbb{U}\Omega/\Gamma$  with fiber  $\mathbb{R}^n$ . (A fiberwise tangent bundle of  $\mathbf{A}$ )

- There is a flat connection  $\nabla^{\mathbf{V}}$  on  $\mathbf{V}$ .

- There are fiberwise metrics denoted by  $\|\cdot\|_{\text{fiber}}$  on  $\mathbf{A}$  and  $\mathbf{V}$  obtainable by partition of unity.
- There is a flow  $\Phi_t : \mathbf{A} \rightarrow \mathbf{A}$ ,  $t \in \mathbb{R}$  acting parallel way on the fibers and acting as a flow on  $\mathbb{U}\Sigma_E$ .
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- Also a flow  $\mathcal{L}(\Phi_t) : \mathbf{V} \rightarrow \mathbf{V}$ .
- The aim is to find a section  $s : \mathbb{U}\Sigma_E \rightarrow \mathbb{A}^n$  “neutral” under flow  $\Phi$ . That is the geodesics goes to an arc varying in only neutral directions.

## Decomposition of $\mathbf{V}$ .

- For each vector  $\vec{u} \in \mathbb{U}\Omega$ , the oriented geodesic  $l$  ending at  $\partial_+ l, \partial_- l \in \text{bd}\Omega$ . correspond to the 1-dim vector subspaces  $\mathbf{V}_+(\vec{u})$  and  $\mathbf{V}_-(\vec{u})$  in  $\mathbb{R}^n$ .

## Decomposition of $\mathbf{V}$ .

- There exists a unique pair of sharply supporting hyperspaces  $H_+$  and  $H_-$  in  $\text{bd}\mathbb{A}^n$  at  $\partial_+ I$  and  $\partial_- I$ . We denote by  $H_0 = H_+ \cap H_-$ , a codimension 2 great sphere in  $\text{bd}\mathbb{A}^n$  and corresponds to a subspace  $\mathbf{V}_0(\vec{u})$  of codimension-two in  $\mathbf{V}$ .

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- For each vector  $\vec{u}$ , we obtain the  $C^0$ -decomposition of  $V$  as  $\mathbf{V}_+(\vec{u}) \oplus \mathbf{V}_0(\vec{u}) \oplus \mathbf{V}_-(\vec{u})$  and form the subbundles  $\tilde{\mathbf{V}}_+, \tilde{\mathbf{V}}_0, \tilde{\mathbf{V}}_-$  over  $\mathbb{U}\Omega$  where  $\tilde{\mathbf{V}} = \tilde{\mathbf{V}}_+ \oplus \tilde{\mathbf{V}}_0 \oplus \tilde{\mathbf{V}}_-$ .

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Since the  $\Gamma$ -action and  $\Phi$  preserves the decomposition of  $\tilde{\mathbf{V}}$ , we obtain the bundle decomposition

$$\mathbf{V} = \mathbf{V}_+ \oplus \mathbf{V}_0 \oplus \mathbf{V}_- \quad (5)$$

invariant under the flow  $\mathcal{L}(\Phi)_t$ .



## Flow properties of $\mathcal{L}(\Phi_t)$

By the uniform middle-eigenvalue condition,  $\mathbf{V}$  satisfies the following properties:

- the flat linear connection  $\nabla^{\mathbf{V}}$  on  $\mathbf{V}$  is bounded with respect to  $\|\cdot\|_{\text{fiber}}$ .

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$$\|\mathcal{L}(\Phi_t)(\vec{v})\|_{\text{fiber}} \geq \frac{1}{C} \exp(kt) \|\vec{v}\|_{\text{fiber}} \text{ as } t \rightarrow \infty \quad (6)$$

for  $\vec{v} \in \mathbf{V}_+$  and

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- Intuitively, these are just from the fact that as one goes along the flow the forward vector must become larger and larger in order for it to be in the same size as in  $\|\cdot\|_{\text{fiber}}$ .

## Proof of the flow properties: $\mathbf{V}_-$ -part only

- Let  $F$  be a compact fundamental domain of  $\Omega$ . We let  $y_i = \Phi_{t_i}(x_i)$ ,  $t_i \rightarrow \infty$ , for  $x_i$  is some compact set  $K$  in  $\mathbb{U}\Omega$ . Let  $l_i$  denote the complete geodesic containing  $x_i, y_i$ .

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- Find a deck transformation  $g_i$  so that  $g_i(y_i) \in F$  and  $g_i$  acts on the line bundle  $\tilde{\mathbf{V}}_-$  by the linearization of the matrix of form of (1):

$$\begin{aligned} \mathcal{L}(g_i) : \mathbf{V}_- &\rightarrow \mathbf{V}_- \text{ given by} \\ (y_i, \vec{v}) &\rightarrow (g_i(y_i), \mathcal{L}(g_i)(\vec{v})) \text{ where} \\ \mathcal{L}(g_i) &= \frac{1}{\lambda_{\tilde{E}}(g_i)^{1+\frac{1}{n}}} \hat{h}(g_i) : \mathbf{V}_-(y_i) = \mathbf{V}_-(x_i) \rightarrow \mathbf{V}_-(g_i(y_i)). \end{aligned} \tag{8}$$

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(Goal) We will show  $\{(g_i(y_i), \mathcal{L}(g_i)(\vec{v}_{-,i}))\} \rightarrow 0$  under  $\|\cdot\|_{\text{fiber}}$ . This will complete the proof since  $g_i$  acts as isometries on  $\mathbf{V}_-$  with  $\|\cdot\|_{\text{fiber}}$ .

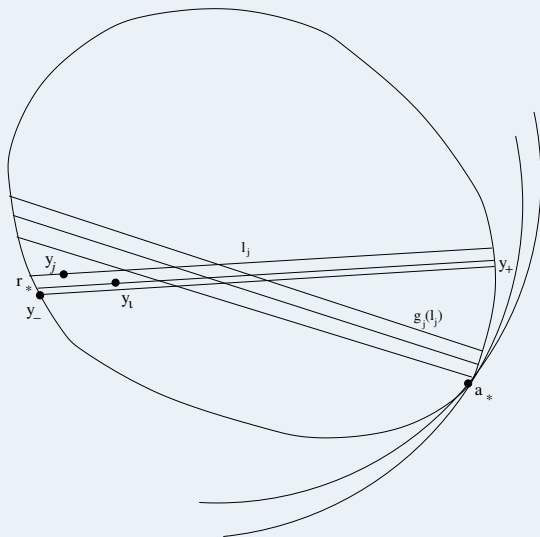


Figure: Pulling back arguments.

## Proof continues

Let  $\|\cdot\|_E$  denote the standard Euclidean metric of  $\mathbb{R}^n$ . Let  $a_i, r_i$  denote the attracting and repelling fixed points of  $g_i$ .

- Since  $\Pi_\Omega(y_i) \rightarrow y_-$ ,  $\Pi_\Omega(y_i)$  is also uniformly bounded away from  $a_i$  and the tangent sphere  $\mathbb{S}_i^{n-1}$  at  $a_i$ .



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- Since  $((\vec{v}_{-,i})) \rightarrow y_-$ , the vector  $\vec{v}_{-,i}$  has the component  $\vec{v}_i^P$  parallel to  $r_i$  and the component  $\vec{v}_i^S$  in the direction of  $\mathbb{S}_i^{n-2}$  where  $\vec{v}_{-,i} = \vec{v}_i^P + \vec{v}_i^S$ .

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- Since  $r_i \rightarrow r_* = y_-$  and  $((\vec{v}_{-,i})) \rightarrow y_-$ , we obtain  $\|\vec{v}_i^S\|_E \rightarrow 0$  and that

$$\frac{1}{C} < \|\vec{v}_i^P\|_E < C$$

for some constant  $C > 1$ .

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- Since  $((\vec{v}_{-,i})) \rightarrow y_-$ , the vector  $\vec{v}_{-,i}$  has the component  $\vec{v}_i^p$  parallel to  $r_i$  and the component  $\vec{v}_i^s$  in the direction of  $\mathbb{S}_i^{n-2}$  where  $\vec{v}_{-,i} = \vec{v}_i^p + \vec{v}_i^s$ .
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for some constant  $C > 1$ .

- $g_i$  acts by preserving the directions of  $\mathbb{S}_i^{n-2}$  and  $r_i$ .

Since  $\{g_i(\vec{v}_{-,i})\}$  converging to  $y'$ ,  $y' \in \text{bd}\Omega$ , is bounded away from  $\mathbb{S}_i^{n-2}$  uniformly, we obtain that

- considering the homogeneous coordinates

$$\left( \left( \mathcal{L}(g_i)(\vec{v}_i^S) : \mathcal{L}(g_i)(\vec{v}_i^P) \right) \right)$$

we obtain that the Euclidean norm of

$$\frac{\mathcal{L}(g_i)(\vec{v}_i^S)}{\|\mathcal{L}(g_i)(\vec{v}_i^P)\|_E}$$

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Since  $r_i$  is a repelling fixed point of  $g_i$  and  $\|\vec{v}_i^P\|_E$  is uniformly bounded above,  $\{\mathcal{L}(g_i)(\vec{v}_i^P)\} \rightarrow 0$  by (3) and  $\text{length}_\Omega(g_i) \rightarrow \infty$ .  $\{\mathcal{L}(g_i)(\vec{v}_i^P)\} \rightarrow 0$  implies  $\{\mathcal{L}(g_i)(\vec{v}_i^S)\} \rightarrow 0$  for  $\|\cdot\|_E$ . Hence, we obtain  $\|\mathcal{L}(g_i)(\vec{v}_{-,i})\|_E \rightarrow 0$ .

## Neutralized sections

$\mathbf{A} := \mathbb{U}\Omega \times \mathbb{A}^n / \Gamma$ . A section  $s : \mathbb{U}\Omega / \Gamma \rightarrow \mathbf{A}$  is *neutralized* if

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### Lemma 2.

A neutralized section  $s_0 : \mathbb{U}\Omega / \Gamma \rightarrow \mathbf{A}$  exists. This lifts to a map  $\tilde{s}_0 : \mathbb{U}\Omega \rightarrow \tilde{\mathbf{A}}$  so that  $\tilde{s}_0 \circ \gamma = \gamma \circ \tilde{s}_0$  for each  $\gamma$  in  $\Gamma$  acting on  $\tilde{\mathbf{A}} = \mathbb{U}\Omega \times \mathbb{A}^n$ .

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### Proof.

We decompose

$$\nabla_{\phi}^{\mathbf{V}}(s) = \nabla_{\phi}^{\mathbf{V}^+}(s) + \nabla_{\phi}^{\mathbf{V}^0}(s) + \nabla_{\phi}^{\mathbf{V}^-}(s) \in \mathbf{V}$$

so that  $\nabla_{\phi}^{\mathbf{V}^{\pm}}(s) \in \mathbf{V}_{\pm}$  and  $\nabla_{\phi}^{\mathbf{V}^0}(s) \in \mathbf{V}_0$  hold. The integrals converge to smooth functions over  $\mathbb{U}\Omega / \Gamma$ :  $s_0 = s + \int_0^{\infty} (D\Phi_t)_*(\nabla_{\phi}^{\mathbf{V}^-}(s))dt - \int_0^{\infty} (D\Phi_{-t})_*(\nabla_{\phi}^{\mathbf{V}^+}(s))dt$  is a continuous section and  $\nabla_{\phi}^{\mathbf{V}}(s_0) = \nabla_{\phi}^{\mathbf{V}^0}(s_0) \in \mathbf{V}_0$  as shown by Goldman-Labourie-Margulis [2]. □



## Finding supporting hyperspaces

- Let  $N_2(\mathbb{A}^n)$  denote the space of codimension-two affine subspaces of  $\mathbb{A}^n$ .
- Each geodesic goes into a neutral affine subspace of codimension two in  $\mathbb{A}^n$ . There exists a continuous function  $\hat{s} : \mathbb{U}\Omega \rightarrow N_2(\mathbb{A}^n)$  equivariant with respect to  $\Gamma$ -actions.

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- Given  $g \in \Gamma$  and for  $\vec{l}_g$  in  $\mathbb{U}\Omega$  where  $g$  acts on,  $\hat{s}(\vec{l}_g) = N_2(g)$ .

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$$\bar{s} : \Lambda^* = \text{bd}\Omega \times \text{bd}\Omega - \Delta \rightarrow N_2(\mathbb{A}^n)$$

is continuous and equivariant wrt the  $\Gamma$ -actions.

### Theorem 3 (Existence of $U$ ).

- Let  $\Gamma$  have an affine action on the affine subspace  $\mathbb{A}^n$ ,  $\mathbb{A}^n \subset \mathbb{S}^n$ , acting properly and cocompactly on a properly convex domain  $\Omega$  in  $\text{bd}\mathbb{A}^n$ .
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- $\Gamma$  satisfies the uniform middle-eigenvalue condition.

Then  $\Gamma$  is asymptotically nice with respect to a properly convex open domain  $U$ .

### Proof.

- We form an affine subspace of codim 1 for each oriented (augmented) geodesic  $l$  by taking an affine span of the backward (augmented) endpoint of  $l$  and the affine subspace  $\hat{s}(\vec{l}_g)$  in  $N_2(\mathbb{A}^n)$ .
- This affine subspace depends only on the backward endpoint of  $l$ .
- Then we form an affine half-space by taking the component containing  $\Omega$  in the boundary.

□

## Theorem 4 (Uniqueness of the set of AS-hyperplanes).

- Let  $\Gamma$  have an affine action on the affine subspace  $\mathbb{A}^n$ ,  $\mathbb{A}^n \subset \mathbb{S}^n$ , acting properly and cocompactly on a properly convex domain  $\Omega$  in  $\text{bd}\mathbb{A}^n$ .
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### Proof of Theorem 1.

Theorems 3 and 4 prove it. □



# Globally hyperbolic spacetime

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- Barbot's technique is that of Mane-Sullivan. One extends the action to parallel null-planes and use contraction properties to obtain the Sullivan stability.

## Duality and R-ends

- Given a properly convex affine action of  $\Gamma$  acting on

$$U \subset \mathbb{A}^n \subset \mathbb{S}^n \text{ and } \Omega \subset \mathbb{S}_\infty^{n-1},$$

the dual group  $\Gamma^*$  will act on  $\mathbb{S}^{n*}$  fixing a pair of points  $p$  and  $p_-$  in  $\mathbb{S}^{n*}$  dual to  $\mathbb{S}_\infty^{n-1}$  with two orientations.

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- There is a fibration  $\partial T_p - \{p, p_-\} \rightarrow \partial \Omega^*$  with fiber a line from  $p$  to  $p_-$ .
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- This gives a lens-domain in  $\mathcal{T}_p$  disjoint from  $\{p, p_-\}$ .



## Lens-shaped R-ends

- A *lens-cone* is a space of form  $\{v\} * L = \{v\} * B$  for a lens  $L$  and a boundary component  $B$  of  $L$ .
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- Such a p-end neighborhood has a foliation by radial segments, and the corresponding end is called a *lens-shaped radial end*.
- Again, the uniform middle eigenvalue condition for the end holonomy group  $\Gamma$  is equivalent to the existence of generalized lens-shaped radial end-neighborhood.

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